Optimal decay rates for the acoustic wave motions with boundary memory damping

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Abstract. A linear wave equation with acoustic boundary conditions (ABC) on a portion of the boundary and Dirichlet conditions on the rest of the boundary is considered. The (ABC) contain a memory damping with respect to the normal displacement of the boundary point. In this paper, we establish polynomial energy decay rates for the wave equation by using resolvent estimates.

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1. Introduction

In this paper we investigate the existence and decay properties of solutions for the initial boundary value problem of the wave equation of the type

\[ \begin{aligned}
    y_{tt}(x, t) - y_{xx}(x, t) &= 0 \quad \text{in } (0, L) \times (0, +\infty), \\
    y(x, t) &= 0 \quad \text{in } (0, +\infty), \\
    y_x(L, t) &= z_t(t) \quad \text{in } (0, +\infty), \\
    y_t(L, t) + mz(t) + \gamma \partial_t^{\alpha,\eta} z(t) &= 0 \quad \text{in } (0, +\infty), \\
    y(x, 0) &= y_0(x), \quad y_t(x, 0) = y_1(x) \quad \text{in } (0, L),
\end{aligned} \]  

(P)

where \((x, t) \in (0, L) \times (0, +\infty), m > 0, \gamma > 0, \eta \geq 0\) and the initial data are taken in suitable spaces. The notation \(\partial_t^{\alpha,\eta}\) stands for the generalized Caputo’s fractional derivative of order \(\alpha, 0 < \alpha < 1\), with respect to the time variable (see Choi and MacCamy [9]). It is defined as follows

\[ \partial_t^{\alpha,\eta} w(t) = \frac{1}{\Gamma(1-\alpha)} \int_0^t (t-s)^{-\alpha} e^{-\eta(t-s)} \frac{dw}{ds}(s) \, ds, \quad \eta \geq 0. \]

The problem \((P)\) describes sound wave propagation in a domain which is full of some kind of medium and with a portion of boundary made of light-weight viscoelastic material.
Acoustic model was proposed by Morse and Ingard [15], and improved in a rigorous mathematical way by Beale and Rosencrens [5]. Under the assumption that each local-reacting boundary point acts as a spring, the author analyzed the model in both bounded and exterior domains in [3], [4]. Uniform energy decay rates were studied in [7], [16] for acoustic wave systems with both internal and boundary memory damping terms. To our knowledge, there has been few work about the decay rates of acoustic wave energies when only one memory damping acting on the acoustic boundary.

Recently, in [11], the authors considered the following initial boundary value problem with memory type acoustic boundary conditions,

\[
\begin{align*}
  y_{tt}(x,t) - \Delta y(x,t) &= 0 & \text{in } \Omega \times (0, +\infty), \\
  y(x,t) &= 0 & \text{in } \Gamma_0 \times (0, +\infty), \\
  \frac{\partial y}{\partial \nu}(x,t) &= z_t(x,t) & \text{in } \Gamma_1 \times (0, +\infty), \\
  y_t(x,t) + mz(x,t) + \gamma \partial_\alpha,0 z(x,t) &= 0 & \text{in } \Gamma_1 \times (0, +\infty), \\
  y(x,0) &= y_0(x), & y_t(x,0) = y_1(x) & \text{in } (0, L).
\end{align*}
\] (P)

They proved well-posedness and strong stability of the system (P) without giving an energy decay rate. Very Recently, in [12] the authors proved that the energy is polynomially stable but without obtaining the precise exponent.

The aim of the present paper is to obtain more precise rates of decay. This can be achieved via some theorems about operator semigroups. We provide a standard method of going from resolvent estimates for a suitable PDE to rates of decay of classical (strong) solutions.

We should mention here that the approach in [11] and [12], which is based on Laplace transform is different from ours. By redescribing the fractional derivative term by means of a suitable diffusion equation as in [14], the original model is transformed into an augmented system which can be more easily tackled by the energy method.

2. Augmented model

This section is concerned with the reformulation of the model (P) into an augmented system. For that, we need the following claims.

**Theorem 2.1 (see [14]).** Let \( \mu \) be the function:

\[
\mu(\xi) = |\xi|^{(2\alpha - 1)/2}, \quad -\infty < \xi < +\infty, \quad 0 < \alpha < 1.
\] (2.1)

Then the relationship between the 'input' \( U \) and the 'output' \( O \) of the system

\[
\partial_t \phi(\xi,t) + (\xi^2 + \eta)\phi(\xi,t) - U(t)\mu(\xi) = 0, \quad -\infty < \xi < +\infty, \eta \geq 0, \ t > 0,
\] (2.2)

\[
\phi(\xi,0) = 0,
\] (2.3)

\[
O(t) = (\pi)^{-1} \sin(\alpha \pi) \int_{-\infty}^{+\infty} \mu(\xi)\phi(\xi,t) \, d\xi
\] (2.4)

is given by

\[
O = I_1^{1-\alpha,\eta} U = D^{\alpha,\eta} U,
\] (2.5)
This completes the proof of the lemma.

Lemma 2.2 (see [1]). If \( \lambda \in D_\eta = \mathbb{C} \setminus ]-\infty, -\eta] \) then

\[
\int_{-\infty}^{+\infty} \frac{\mu^2(\xi)}{\lambda + \eta + \xi^2} \, d\xi = \frac{\pi}{\sin \alpha \pi} (\lambda + \eta)^{\alpha-1}.
\]

We are now in a position to reformulate system \((P)\). Indeed, by using Theorem 2.1, system \((P)\) may be recast into the augmented model:

\[
\begin{align*}
&\begin{cases}
y_{tt}(x,t) - y_{xx}(x,t) = 0 & \text{in } (0, L) \times (0, +\infty), \\
\partial_t \phi(x,t) + (\xi^2 + \eta) \phi(x,t) - z_t(t) \mu(\xi) = 0 & \text{in } (0, +\infty) \times (0, +\infty), \\
y(0,t) = 0 & \text{in } (0, +\infty), \\
y_x(L,t) = z_t(t) & \text{in } (0, +\infty), \\
y_t(L,t) + m z(t) + \zeta \int_{-\infty}^{+\infty} \mu(\xi) \phi(\xi,t) \, d\xi = 0 & \text{in } (0, +\infty), \\
y(x,0) = y_0(x), \quad y_t(x,0) = y_1(x) & \text{in } (0, L), \\
\phi(\xi,0) = 0 & \text{in } (-\infty, +\infty).
\end{cases}
\end{align*}
\]

\[\text{(P')}\]

We define the energy associated to the solution of the problem \((P')\) by the following formula:

\[
E(t) = \frac{1}{2} \|y_t\|^2_2 + \frac{1}{2} \|y_x\|^2_2 + \frac{m}{2} \|z(t)\|^2 + \frac{\zeta}{2} \int_{-\infty}^{+\infty} \|\phi(\xi,t)\|^2 \, d\xi. \tag{2.6}
\]

Lemma 2.3. Let \((y, \phi)\) be a solution of the problem \((P')\). Then, the energy functional defined by (2.6) satisfies

\[
E'(t) = -\zeta \int_{-\infty}^{+\infty} (\xi^2 + \eta) \|\phi(\xi,t)\|^2 \, d\xi \leq 0. \tag{2.7}
\]

Proof. Multiplying the first equation in \((P')\) by \(\overline{y}_t\), integrating over \((0, L)\) and using integration by parts, we get

\[
\frac{1}{2} \frac{d}{dt} \|y_t\|^2_2 - \Re \int_0^L y_{xx} \overline{y}_t \, dx = 0.
\]

Then

\[
\frac{d}{dt} \left( \frac{1}{2} \|y_t\|^2_2 + \frac{1}{2} \|y_x\|^2_2 \right) + \Re z(t) \left( m \overline{z}(t) + \zeta \int_{-\infty}^{+\infty} \mu(\xi) \overline{\phi}(\xi,t) \, d\xi \right) = 0. \tag{2.8}
\]

Multiplying the second equation in \((P')\) by \(\zeta \overline{\phi}_t\) and integrating over \((-\infty, +\infty)\), to obtain:

\[
\frac{\zeta}{2} \frac{d}{dt} \|\phi\|^2_2 + \zeta \int_{-\infty}^{+\infty} \|\phi(\xi,t)\|^2 \, d\xi - \zeta \Re z(t) \int_{-\infty}^{+\infty} \mu(\xi) \overline{\phi}(\xi,t) \, d\xi = 0. \tag{2.9}
\]

From (2.6), (2.8) and (2.9) we get

\[
E'(t) = -\zeta \int_{-\infty}^{+\infty} (\xi^2 + \eta) \|\phi(\xi,t)\|^2 \, d\xi.
\]

This completes the proof of the lemma. \(\square\)
3. Well-posedness

The energy space associated to system \((P)\) is

\[
\mathcal{H} = H^1_L(0, L) \times L^2(0, L) \times L^2(-\infty, +\infty) \times \mathbb{C}, \quad H^1_L(0, L) = \{ y \in H^1(0, L), \ y(0) = 0 \}
\]
equipped with the inner product

\[
<U, \tilde{U}>_{\mathcal{H}} = \int_{\Omega} (v \tilde{v} + y x \tilde{y} x + m z \tilde{z}) + \int_{-\infty}^{+\infty} \phi \tilde{\phi} d\xi,
\]

where \(U = (y, v, \phi, z)^T, \tilde{U} = (\tilde{y}, \tilde{v}, \tilde{\phi}, \tilde{z})^T \in \mathcal{H}\).

Let \(U = (y, y_t, \phi, z)^T\) and rewrite \((P')\) as

\[
\begin{cases}
U' = AU, \\
U(0) = (y_0, y_1, \phi_0, z_0),
\end{cases}
\]

where the operator \(A\) is defined by

\[
A \begin{pmatrix} y \\ v \\ \phi \\ z \end{pmatrix} = \begin{pmatrix} v \\ y_{xx} \\ -(\xi^2 + \eta)\phi + y_x(L)\mu(\xi) \\ y_x(L) \end{pmatrix}
\]

with domain

\[
D(A) = \left\{ (y, v, \phi, z)^T \in \mathcal{H} : y \in H^2(0, L) \cap H^1_L(0, L), \right. \\
\left. v \in H^1_L(0, L), z \in \mathbb{C}, \right. \\
\left. -(\xi^2 + \eta)\phi + y_x(L)\mu(\xi) \in L^2(-\infty, +\infty), \right. \\
\left. |\xi|\phi \in L^2(-\infty, +\infty) \right\}.
\]

Now, we will give well-posedness results for problem \((P)\) using semigroup theory. We show that the operator \(A\) generates a \(C_0\)-semigroup in \(\mathcal{H}\). We prove that \(A\) is a maximal dissipative operator (see [8]). For this purpose we need the following two lemmas.

**Lemma 3.1.** The operator \(A\) is dissipative and satisfies, for any \(U \in D(A)\),

\[
\Re \langle AU, U \rangle_{\mathcal{H}} = -\xi \int_{-\infty}^{+\infty} (\xi^2 + \eta)|\phi(\xi)|^2 d\xi.
\]

**Proof.** For any \(U = (y, v, \phi, z)^T \in D(A)\), Using (3.1) and the fact that

\[
||(y, y_t, \phi, z)||^2_{\mathcal{H}} = ||U||^2_{\mathcal{H}},
\]

estimate (3.4) easily follows.

\[
\square
\]

**Lemma 3.2.** The operator \(\lambda I - A\) is surjective for all \(\lambda > 0\).

**Proof.** We need to show that for all \(F = (f_1, f_2, f_3, f_4)^T \in \mathcal{H}\), there exists

\[
U = (y, u, \phi, v)^T \in D(A)
\]
such that

\[
\lambda U - AU = F,
\]

\[
\square
\]
that is
\[
\begin{align*}
\lambda y - v &= f_1, \\
\lambda v - y_{xx} &= f_2, \\
\lambda \phi + (\xi^2 + \eta)\phi - y_x(L)\mu(\xi) &= f_3, \\
\lambda z - y_x(L) &= f_4.
\end{align*}
\] (3.7)

Suppose that we have found \( y \). Therefore, the first equation in (3.7) gives
\[
v = \lambda y - f_1.
\] (3.8)

It is clear that \( u \in H^1_L(0, L) \). Furthermore, by (3.7) we can find \( \phi \) as
\[
\phi = \frac{f_3(\xi) + \mu(\xi)y_x(L)}{\xi^2 + \eta + \lambda}.
\] (3.9)

By using (3.7) and (3.8) the function \( y \) satisfying the following system
\[
\lambda^2 y - y_{xx} = f_2 + \lambda f_1.
\] (3.10)

Solving system (3.10) is equivalent to finding \( y \in H^2 \cap H^1_L(0, L) \) such that
\[
\int_0^L (\lambda^2 y \bar{w} - y_{xx} \bar{w}) \, dx = \int_0^L (f_2 + \lambda f_1) \bar{w} \, dx,
\] (3.11)

for all \( \bar{w} \in H^1_L(0, L) \). By using (3.11) and (3.9) the function \( y \) satisfying the following system
\[
\begin{align*}
&\int_0^L (\lambda^2 y \bar{w} + y_x \bar{w}_x) \, dx + \frac{\lambda^2}{m + \gamma \lambda (\lambda + \eta)^{\alpha-1}} y(L) \bar{w}(L) \\
&= \int_0^L (f_2 + \lambda f_1) \bar{w} \, dx + \frac{1}{m + \gamma \lambda (\lambda + \eta)^{\alpha-1}} (\lambda f_1(L) \\
&- \zeta \lambda \int_{-\infty}^{+\infty} \frac{\mu(\xi)}{\xi^2 + \eta + \lambda} f_3(\xi) \, d\xi - mf_4 \bar{w}(L).
\end{align*}
\] (3.12)

Consequently, problem (3.12) is equivalent to the problem
\[
a(y, w) = L(w),
\] (3.13)

where the sesquilinear form \( a : H^1_L(0, L) \times H^1_L(0, L) \to \mathbb{C} \) and the antilinear form \( L : H^1_L(0, L) \to \mathbb{C} \) are defined by
\[
a(y, w) = \int_0^L (\lambda^2 y \bar{w} + y_x \bar{w}_x) \, dx + \frac{\lambda^2}{m + \gamma \lambda (\lambda + \eta)^{\alpha-1}} y(L) \bar{w}(L)
\]

and
\[
L(w) = \int_0^L (f_2 + \lambda f_1) \bar{w} \, dx + \frac{1}{m + \gamma \lambda (\lambda + \eta)^{\alpha-1}} (\lambda f_1(L) \\
&- \zeta \lambda \int_{-\infty}^{+\infty} \frac{\mu(\xi)}{\xi^2 + \eta + \lambda} f_3(\xi) \, d\xi - mf_4 \bar{w}(L).
\]

It is easy to verify that \( a \) is continuous and coercive, and \( L \) is continuous. So applying the Lax-Milgram theorem, we deduce that for all \( w \in H^1_L(0, L) \) problem (3.13) admits a unique solution \( y \in H^1_L(0, L) \). Applying the classical elliptic regularity, it follows from (3.12) that \( y \in H^2(0, L) \). Therefore, the operator \( \lambda I - A \) is surjective for any \( \lambda > 0 \). \( \square \)
Consequently, using Hille-Yosida Theorem, we have the following well-posedness result:

Theorem 3.3 (Existence and uniqueness).

1. If \( U_0 \in D(A) \), then system (3.1) has a unique strong solution 
   \[ U \in C^0(\mathbb{R}_+, D(A)) \cap C^1(\mathbb{R}_+, \mathcal{H}). \]
2. If \( U_0 \in \mathcal{H} \), then system (3.1) has a unique weak solution 
   \[ U \in C^0(\mathbb{R}_+, \mathcal{H}). \]

4. Lack of exponential stability

In order to state and prove our stability results, we need the following well known theorems.

Theorem 4.1 ([17]-[10]). Let \( S(t) = e^{At} \) be a \( C_0 \)-semigroup of contractions on Hilbert space \( \mathcal{H} \). Then \( S(t) \) is exponentially stable if and only if 
\[ \rho(A) \supseteq \{ i\beta : \beta \in \mathbb{R} \} \equiv i\mathbb{R} \]
and
\[ \lim_{|\beta| \to \infty} \| (i\beta \mathbb{I} - A)^{-1} \|_{L(\mathcal{H})} < \infty. \]

Theorem 4.2 ([6]). Let \( S(t) = e^{At} \) be a \( C_0 \)-semigroup on a Hilbert space \( \mathcal{H} \). If 
\[ i\mathbb{R} \subset \rho(A) \text{ and } \sup_{|\beta| \geq 1} \frac{1}{\beta^\delta} \| (i\beta \mathbb{I} - A)^{-1} \|_{L(\mathcal{H})} \leq M \]
for some \( \delta > 0 \), then there exist \( \epsilon \) such that 
\[ \| e^{At} U_0 \|^2 \leq \frac{C}{t^\delta} \| U_0 \|^2_{D(A)}. \]

Theorem 4.3 ([2]-[13]). Let \( A \) be the generator of a uniformly bounded \( C_0 \)-semigroup \( \{ S(t) \}_{t \geq 0} \) on a Hilbert space \( \mathcal{H} \). If:

(i) \( A \) does not have eigenvalues on \( i\mathbb{R} \).
(ii) The intersection of the spectrum \( \sigma(A) \) with \( i\mathbb{R} \) is at most a countable set, 
then the semigroup \( \{ S(t) \}_{t \geq 0} \) is asymptotically stable, i.e, \( \| S(t)z \|_{\mathcal{H}} \to 0 \) as \( t \to \infty \) for any \( z \in \mathcal{H} \).

Our main first result is

Theorem 4.4. The semigroup generated by the operator \( A \) is not exponentially stable.

Proof. We will examine two cases.

- **Case 1.** \( \eta = 0 \): We shall show that \( i\lambda = 0 \) is not in the resolvent set of the operator \( A \). Indeed, noting that \((0, 0, 0, \cos L)^T \in \mathcal{H} \), and denoting by \((y, v, \phi, z)^T \) the image of \((0, 0, 0, \cos L)^T \) by \( A^{-1} \), we see that \( \phi(\xi) = |\xi|^{\frac{2n-2}{2}} \cos L \). But, then \( \phi \notin L^2(-\infty, +\infty) \), since \( \alpha \in ]0, 1[. \) Hence \((y, v, \phi, z)^T \notin D(A) \).

- **Case 2.** \( \eta \neq 0 \): We aim to show that an infinite number of eigenvalues of \( A \) approach the imaginary axis which prevents the wave system (P) from being exponentially
stable. Indeed we first compute the characteristic equation that gives the eigenvalues of \( \mathbf{A} \). Let \( \lambda \) be an eigenvalue of \( \mathbf{A} \) with associated eigenvector \( \mathbf{U} = (y, v, \phi, z)^T \). Then \( \mathbf{AU} = \lambda \mathbf{U} \) is equivalent to

\[
\begin{align*}
\lambda y - v &= 0, \\
\lambda v - y_{xx} &= 0, \\
\lambda \phi + (\xi^2 + \eta) \phi - y_x(L) \mu(\xi) &= 0, \\
\lambda z - y_x(L) &= 0, \\
v(L) + mz + \zeta \int_{-\infty}^{+\infty} \mu(\xi) \phi(\xi) \, d\xi &= 0.
\end{align*}
\] (4.1)

From (4.1)_1 - (4.1)_2 for such \( \lambda \), we find
\[
\lambda^2 y - y_{xx} = 0.
\] (4.2)

Since \( v = \lambda y(L) \), using (4.1)_3 and (4.1)_4, we get
\[
\begin{align*}
y(0) &= 0, \\
\lambda^2 y(L) + (m + \gamma \lambda (\lambda + \eta)^{\alpha-1}) y_x(L) &= 0.
\end{align*}
\] (4.3)

The solution \( y \) is given by
\[
y(x) = \sum_{i=1}^{2} c_i e^{t_i x},
\] (4.4)

where
\[
t_1(\lambda) = \lambda, \quad t_2(\lambda) = -\lambda.
\]

Thus the boundary conditions may be written as the following system:
\[
M(\lambda) C(\lambda) = \begin{pmatrix} 1/h(t_1) e^{t_1 L} & 1/h(t_2) e^{t_2 L} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}
\] (4.5)

where we have set
\[
h(r) = (m + \gamma \lambda (\lambda + \eta)^{\alpha-1}) r + \lambda^2.
\]

Hence a non-trivial solution \( y \) exists if and only if the determinant of \( M(\lambda) \) vanishes. Set \( f(\lambda) = \det M(\lambda) \), thus the characteristic equation is \( f(\lambda) = 0 \).

Our purpose is to prove, thanks to Rouché’s Theorem, that there is a subsequence of eigenvalues for which their real part tends to 0.

In the sequel, since \( \mathbf{A} \) is dissipative, we study the asymptotic behavior of the large eigenvalues \( \lambda \) of \( \mathbf{A} \) in the strip \(-\alpha_0 \leq \Re(\lambda) \leq 0\), for some \( \alpha_0 > 0 \) large enough and for such \( \lambda \), we remark that \( e^{t_i}, i = 1, 2 \) remains bounded.

**Lemma 4.5.** There exists \( N \in \mathbb{N} \) such that
\[
\{ \lambda_k \}_{k \in \mathbb{Z}, |k| \geq N} \subset \sigma(\mathbf{A})
\] (4.6)

where
\[
\lambda_k = \frac{i k \pi}{L} + \frac{\bar{\alpha}}{k^{1-\alpha}} + \frac{\beta}{k^{1-\alpha}} + o \left( \frac{1}{k^{1-\alpha}} \right), \quad k \geq N, \bar{\alpha} \in i\mathbb{R}, \beta \in \mathbb{R}, \beta < 0,
\]

\[
\lambda_k = \overline{\lambda_{-k}} \text{ if } k \leq -N.
\]

Moreover for all \( |k| \geq N \), the eigenvalues \( \lambda_k \) are simple.
Proof. Step 1.

\[ f(\lambda) = e^{t_2 h(t_2)} - e^{t_1 h(t_1)} = -e^{-\lambda L}((m + \gamma \lambda (\lambda + \eta)^{\alpha - 1}) + \lambda) \left( e^{2\lambda L} - \frac{\lambda - (m + \gamma \lambda (\lambda + \eta)^{\alpha - 1})}{\lambda + (m + \gamma \lambda (\lambda + \eta)^{\alpha - 1})} \right) \]  

We set

\[ \tilde{f}(\lambda) = e^{2\lambda L} - 1 + 2\frac{m + \gamma \lambda (\lambda + \eta)^{\alpha - 1}}{m + \lambda + \gamma \lambda (\lambda + \eta)^{\alpha - 1}} \]  

where

\[ f_0(\lambda) = e^{2\lambda L} - 1, \quad f_1(\lambda) = 2\gamma. \]  

Step 2. We look at the roots of \( f_0 \). From (4.9), \( f_0 \) has one family of roots that we denote \( \lambda_0^k \).

\[ f_0(\lambda) = 0 \iff e^{2\lambda L} = 1. \]  

Hence

\[ 2\lambda L = i2k\pi, \quad k \in \mathbb{Z}, \]  

i.e.,

\[ \lambda_0^k = \frac{ik\pi}{L}, \quad k \in \mathbb{Z}. \]  

Now with the help of Rouche’s Theorem, we will show that the roots of \( \tilde{f} \) are close to those of \( f_0 \). Changing in (4.8) the unknown \( \lambda \) by \( u = 2\lambda L \) then (4.8) becomes

\[ \tilde{f}(u) = (e^u - 1) + O \left( \frac{1}{u} \right) = f_0(u) + O \left( \frac{1}{u} \right). \]  

The roots of \( f_0 \) are \( u_k = \frac{ik\pi}{L}, k \in \mathbb{Z} \), and setting \( u = u_k + re^{it}, t \in [0, 2\pi] \), we can easily check that there exists a constant \( C > 0 \) independent of \( k \) such that \( |e^u - 1| \geq Cr \) for \( r \) small enough. This allows to apply Rouche’s Theorem. Consequently, there exists a subsequence of roots of \( \tilde{f} \) which tends to the roots \( u_k \) of \( f_0 \). Equivalently, it means that there exists \( N \in \mathbb{N} \) and a subsequence \( \{\lambda_k\}_{|k| \geq N} \) of roots of \( f(\lambda) \), such that \( \lambda_k = \lambda_0^k + o(1) \) which tends to the roots \( \frac{ik\pi}{L} \) of \( f_0 \). Finally for \( |k| \geq N, \lambda_k \) is simple since \( \lambda_0^k \) is.

Step 3. From Step 2, we can write

\[ \lambda_k = i\frac{1}{L}k\pi + \varepsilon_k. \]  

Using (4.11), we get

\[ e^{2\lambda_k L} = 1 + 2L\varepsilon_k + 2L^2\varepsilon_k^2 + o(\varepsilon_k^2). \]  

(4.12)
Substituting (4.12) into (4.8), using that \( \tilde{f}(\lambda_k) = 0 \), we get:

\[
\tilde{f}(\lambda_k) = 2L\varepsilon_k + \frac{2\gamma}{(k\pi/L + \varepsilon_k)^{1-\alpha}} + o(\varepsilon_k) + o(1/k)
\]

and hence

\[
\varepsilon_k = -\frac{\gamma}{L^\alpha (k\pi)^{1-\alpha}} \left( \cos(1 - \alpha) \frac{\pi}{2} - i \sin(1 - \alpha) \frac{\pi}{2} \right) + o \left( \frac{1}{k^{1-\alpha}} \right) \quad \text{for } k \geq 0.
\]

From (4.13) we have in that case \(|k|^{1-\alpha} R \lambda_k \sim \beta\), with \[
\beta = -\frac{\gamma}{L^\alpha (1-\alpha)} \cos(1 - \alpha) \frac{\pi}{2}.
\]

The operator \( A \) has a non exponential decaying branch of eigenvalues. Thus the proof is complete. \( \square \)

5. Polynomial stability and optimality (for \( \eta \neq 0 \))

In the previous section, we have shown that the transmission wave system is not exponentially stable. In this section, we prove that it is polynomially stable with an optimal rate of decay when \( \eta > 0 \). To achieve this, we use a recent result by Borichev and Tomilov \[6\]. Accordingly, if we consider a bounded \( C_0 \)-semigroup \( S(t) = e^{A t} \) on a Hilbert space. If

\[
i \mathbb{R} \subset \rho(A) \quad \text{and} \quad \lim_{|\beta| \to \infty} \frac{1}{\beta^\delta} \| (i\beta I - A)^{-1} \|_{L(\mathcal{H})} < \infty
\]

for some \( \delta > 0 \), then there exist \( c \) such that

\[
\| e^{At} U_0 \|_2^2 \leq \frac{c}{t^{\frac{2}{1-\alpha}}} \| U_0 \|_{D(A)}^2.
\]

Our main result is as follows.

**Theorem 5.1.** The semigroup \( S_A(t) \) is polynomially stable and

\[
E(t) = \| S_A(t) U_0 \|_2^2 \leq \frac{1}{t^{2/(1-\alpha)}} \| U_0 \|_{D(A)}^2.
\]

Moreover, the rate of energy decay \( t^{-2/(1-\alpha)} \) is optimal for any initial data in \( D(A) \).

**Proof.** We will need to study the resolvent equation \((i\lambda - A)U = F\), for \( \lambda \in \mathbb{R} \), namely

\[
\begin{cases}
  i\lambda y - v = f_1, \\
  i\lambda v - y_{xx} = f_2, \\
  i\lambda \phi + (\xi^2 + \eta) \phi - y_x(L) \mu(\xi) = f_3, \\
  i\lambda z - y_x(L) = f_4
\end{cases}
\]

with the boundary condition

\[
v(L) + mz + \zeta \int_{-\infty}^{+\infty} \mu(\xi) \phi(\xi) \, d\xi = 0.
\]

Acoustic wave motions with boundary memory damping
We divide the proof into three steps, as follows:

**Step 1.** Inserting (5.1) into (5.2), we get
\[ \lambda^2 y + y_{xx} = -(f_2 + i\lambda f_1). \]
As \( y(0) = 0 \), then
\[ y(x) = c_1 \sin \lambda x - \frac{1}{\lambda} \int_0^x (f_2(\sigma) + i\lambda f_1(\sigma)) \sin \lambda(x - \sigma) \, d\sigma, \quad (5.3) \]
and hence
\[ y_x(x) = c_1 \lambda \cos \lambda x - \int_0^x (f_2(\sigma) + i\lambda f_1(\sigma)) \cos \lambda(x - \sigma) \, d\sigma. \quad (5.4) \]

**Step 2.** With the third equation of (5.1), we get
\[ \phi(\xi) = \frac{y_x(L)\mu(\xi) + f_3(\xi)}{i\lambda + \xi^2 + \eta}. \quad (5.5) \]
Inserting (5.5) in the boundary condition (5.2), we easy to check that
\[ -\lambda^2 y(L) + (m + \gamma i\lambda(i\lambda + \eta)^{\alpha - 1})y_x(L) = i\lambda f_1(L) - mf_4 - \zeta i\lambda \int_{-\infty}^{+\infty} \frac{\mu(\xi)f_3(\xi)}{i\lambda + \xi^2 + \eta} \, d\xi. \quad (5.6) \]
Using (5.3) and (5.4), we can rewrite (5.6) as an equation in the unknown \( c_1 \),
\[ c_1(-\lambda^2 \sin \lambda L + \lambda(m + \gamma i\lambda(i\lambda + \eta)^{\alpha - 1}) \cos \lambda L) \]
\[ = i\lambda f_1(L) - mf_4 - \zeta i\lambda \int_{-\infty}^{+\infty} \frac{\mu(\xi)f_3(\xi)}{i\lambda + \xi^2 + \eta} \, d\xi - \lambda \int_0^L (f_2(\sigma) + i\lambda f_1(\sigma)) \sin \lambda(L - \sigma) \, d\sigma \]
\[ + (m + \gamma i\lambda(i\lambda + \eta)^{\alpha - 1}) \int_0^L (f_2(\sigma) + i\lambda f_1(\sigma)) \cos \lambda(L - \sigma) \, d\sigma. \quad (5.7) \]

**Step 3.** We set
\[ g(\lambda) = -\lambda \sin \lambda L + (m + \gamma i\lambda(i\lambda + \eta)^{\alpha - 1}) \cos \lambda L. \quad (5.8) \]
As \( f_1 \in H^1_L(0, L) \) and \( f_2 \in L^1(0, L) \), we have
\[ \left| \int_0^L (f_2(\sigma) + i\lambda f_1(\sigma)) \sin \lambda(L - \sigma) \, d\sigma \right| \leq c(\|f_2\|_{L^2(0, L)} + \|f_1\|_{H^1(0, L)}). \]
\[ \left| \int_0^L (f_2(\sigma) + i\lambda f_1(\sigma)) \cos \lambda(L - \sigma) \, d\sigma \right| \leq c(\|f_2\|_{L^2(0, L)} + \|f_1\|_{H^1(0, L)}). \]
As \( g(\lambda) \neq 0 \) for all \( \lambda \) (if \( \eta = 0 \) then for all \( \lambda \neq 0 \)), then \( c_1 \) is uniqueley determined by (5.7). Hence the operator \( i\lambda - A \) is surjective for all \( \lambda \) (if \( \eta = 0 \) then for all \( \lambda \neq 0 \)). Moreover, taking account of Lemma 4.5, the operator \( i\lambda - A \) is injective for all \( \lambda \). Then \( i\mathbb{R} \subset \rho(A) \) (if \( \eta = 0 \) then \( i\mathbb{R}^* \subset \rho(A) \)).

Moreover, we can easily prove that
\[ |g(\lambda)| \geq c|\lambda|^\alpha \text{ for } \lambda \text{ large}. \]
Hence
\[ |c_1| \leq c|\lambda|^{-\alpha} \text{ for } \lambda \text{ large}. \]
Then, we deduce that
\[ \|y_x\|_{L^2(0,L)} \leq c|\lambda|^{1-\alpha} \text{ for } \lambda \text{ large.} \]
\[ \|v\|_{L^2(0,L)} \leq c|\lambda|^{1-\alpha} \text{ for } \lambda \text{ large.} \]
\[ |z| \leq c|\lambda|^{-\alpha} \text{ for } \lambda \text{ large.} \]

Moreover from (3.4), we have
\[ \|\phi\|^2_{L^2(-\infty,\infty)} \leq \int_{-\infty}^{+\infty} (\xi^2 + \eta) |\phi(\xi)|^2 \, d\xi \leq c\|U\|_{\mathcal{H}}\|F\|_{\mathcal{H}}. \]

Thus, we conclude that
\[ \|(i\lambda I - A)^{-1}\|_{\mathcal{H}} \leq c|\lambda|^{1-\alpha} \text{ as } |\lambda| \to \infty. \] (5.9)

The conclusion then follows by applying the Theorem 4.2. Besides, we prove that the decay rate is optimal. Indeed, the decay rate is consistent with the asymptotic expansion of eigenvalues which show a behavior of the real part like \( k^{-(1-\alpha)} \).

**Remark 5.2.** The method developed in this paper is direct and very flexible; it can be applied to various dissipative problems. In particular, we will consider in the future more general acoustic wave motions and also multidimensional cases under some geometric control conditions.

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