SYLLABUS

programme
Babeş-Bolyai University
Faculty of Mathematics and Computer Science
Department of Mathematics
Computer Science
Bachelor
Computer Science

1. Information regarding the programme

2. Information regarding the discipline

2.1 Name of the disc	ipli	ne Geometry	Geometry				
2.2 Course coordinator			Lect. Dr. Iulian Simion				
2.3 Seminar coordinator			Le	ect. Dr. Iulian Simion			
2.4 Year of study	1	2.5 Semester	2	2.6. Type of evaluation	VP	2.7 Type of	Compulsory
						discipline	
2.8 Disciplinei code MLE0014							

3. Total estimated time (hours/semester of didactic activities)

3.1 Hours per week	4	Of which: 3.2 course	2	3.3 seminar	2
3.4 Total hours in the curriculum	56	Of which: 3.5 course	28	3.6 seminar	28
Time allotment:					hours
Learning using manual, course support,	biblio	graphy, course notes			20
Additional documentation (in libraries, on electronic platforms, field documentation)					10
Preparation for seminars/labs, homework, papers, portfolios and essays					14
Tutorship					14
Evaluations					11
Other activities:					-
3.7 Total individual study hours69					
3.8 Total hours per semester 125					
3.9 Number of ECTS credits 5					

4. Prerequisites (if necessary)

4.1 curriculum	Basic knowledege in algebra and calculus.
4.2 competencies	Competencies of using the above mentioned curricula.

5. Conditions (if necessary)

5.1 for the course	
5.2 for the seminar /lab activities	

6. Specific competencies acquired

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ncies	• C1.1 Idetifying the notions, describing the theories and using the specific language
Professional competencies	• C2.3 Applying the adequate analytical theoretical methods to a given problem
ansversal competencies	CT1. Applying some rules of precise and efficient work, showing a responsible attitude regarding the the scientific domain and teaching training for an optimal and creative
npete	development of the personal potential in specific situations, respecting the deontological
al cor	norms.
svers	
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7. Objectives of the discipline (outcome of the acquired competencies)

7.1 General objective of the	Basic notions and methods în the context of analytic geometry
discipline	
7.2 Specific objective of the	Classification of quadratic curves and surfaces
discipline	

8. Content

8.1 Course	Teaching methods	Remarks
1-2. Affine spaces	Exposition, proofs,	Two lectures
Geometric vectors	examples	
Vector space structure		
Cartesian coordinate frames		
Changing coordinates		
• Affine subspaces in dimension 2 and 3		
Hyperplanes		
3-4. Euclidean spaces	Exposition, proofs,	Two lectures
Scalar product	examples	
Gram matrix		
Orthonormal frames		
Gram-Schmidt process		
Applications		
Spectral Theorem		
5. Orientation	Exposition, proofs,	
Box product	examples	
Cross product		

Properties		
Applications		
6. Affine maps	Exposition, proofs,	
Parallel projections and reflections	examples	
 Orthogonal projections and reflections 	cxumpics	
7. Isometries	Exposition, proofs,	
Rotations in dimension 2 and 3	examples	
 Displacements 	examples	
 Classification of isometries in dimension 2 		
and 3		
8-9. Quadratic curves	Exposition, proofs,	Two lectures
Ellipse, hyperbola, parabola	examples	1 wo lectures
Canonical equations	examples	
Relative position of a line		
*		
Tangent lines Description of quadrics (dimension 2 and 3)	Exposition, proofs,	
10. Classification of quadrics (dimension 2 and 3)Reducing to canonical form	examples	
_	examples	
 Isometric classification of quadrics Affine classification of quadrics 		
Affine classification of quadrics 11-12. Quadratic surfaces	Exposition proofs	Two lectures
 Ellipsoid, Cone, Hyperboloid, Paraboloid 	Exposition, proofs, examples	1 wo lectures
	examples	
 Canonical equation Tangent planes 		
Tangent planes 13. Curvatures	Europition proofs	
Curvatures Curvature of curves	Exposition, proofs,	
Curvature of curves Curvatures of surfaces	examples	
	Exposition proofs	
14. Quaternions	Exposition, proofs,	
 Algebraic description Outermions and retations 	examples	
Quaternions and rotations		
Bibliography		
[1] I. Simion, Geometry – material de curs, 2024.		
[2] P.A. Blaga, Geometrie – material de curs, 2019.[3] M. Troyanov, Cours de géométrie, Lausanne, 20	11	
		di) 2000
[4] E. Sernesi, Linear Algebra. A geometric Approad 8.2 Seminar	Teaching methods	Remarks
1-2. Affine spaces	Dialog, problem solving	Two tutorials
Geometric vectors		
Vector space structure		
Cartesian coordinate frames		
Changing coordinates		
 Affine subspaces in dimension 2 and 3 		
Affilie subspaces in dimension 2 and 5Hyperplanes		
3-4. Euclidean spaces	Dialog, problem solving	Two tutorials
Scalar product		1 WU (UIUIIAIS

 Gram matrix Orthonormal frames Gram-Schmidt process Applications Spectral Theorem Dialog, problem solving Properties Applications Properties Applications Dialog, problem solving Parallel projections and reflections Orthogonal projections and reflections Orthogonal projections and reflections Classification of isometries in dimension 2 and 3 Bialog, problem solving Two tutorials 			
 Gram-Schmidt process Applications Spectral Theorem Spectral Theorem Dialog, problem solving Box product Box product Cross product Properties Applications Properties Applications Dialog, problem solving Botapproblem solving Properties Applications Botapproblem solving Properties Applications Dialog, problem solving Properties Dialog, problem solving Properties Dialog, problem solving Classification of isometries in dimension 2 Again and 3 			
 Applications Spectral Theorem Dialog, problem solving Box product Box product Cross product Cross product Properties Applications Applications Dialog, problem solving Parallel projections and reflections Orthogonal projections and reflections Orthogonal projections and reflections Orthogonal projections and reflections Classification of isometries in dimension 2 and 3 Classification of isometries in dimension 2 and 3 			
 Spectral Theorem Spectral Theorem Dialog, problem solving Box product Box product Cross product Cross product Properties Applications Spectral Theorem Dialog, problem solving Dialog, problem solving Dialog, problem solving Parallel projections and reflections Orthogonal projections and reflections Orthogonal projections and reflections Rotations in dimension 2 and 3 Displacements Classification of isometries in dimension 2 and 3 			
5. OrientationDialog, problem solving• Box product-• Cross product-• Properties-• Applications-6. Affine mapsDialog, problem solving• Parallel projections and reflections-• Orthogonal projections and reflections-7. IsometriesDialog, problem solving• Rotations in dimension 2 and 3-• Classification of isometries in dimension 2 and 3-			
 Box product Cross product Properties Applications Applications Dialog, problem solving Parallel projections and reflections Orthogonal projections and reflections Orthogonal projections and reflections T. Isometries Rotations in dimension 2 and 3 Displacements Classification of isometries in dimension 2 and 3 			
 Cross product Properties Applications Applications Dialog, problem solving Parallel projections and reflections Orthogonal projections and reflections Orthogonal projections and reflections T. Isometries Rotations in dimension 2 and 3 Classification of isometries in dimension 2 and 3 			
 Properties Applications Applications Dialog, problem solving Parallel projections and reflections Orthogonal projections and reflections Orthogonal projections and reflections T. Isometries Rotations in dimension 2 and 3 Displacements Classification of isometries in dimension 2 and 3 			
ApplicationsImage: Construct on the second seco			
6. Affine mapsDialog, problem solving• Parallel projections and reflectionsDialog, problem solving• Orthogonal projections and reflectionsDialog, problem solving7. IsometriesDialog, problem solving• Rotations in dimension 2 and 3Dialog, problem solving• Classification of isometries in dimension 2 and 3Image: Classification of isometries in dimension 2 and 3			
 Parallel projections and reflections Orthogonal projections and reflections Orthogonal projections and reflections T. Isometries Rotations in dimension 2 and 3 Displacements Classification of isometries in dimension 2 and 3 			
 Orthogonal projections and reflections Isometries Rotations in dimension 2 and 3 Displacements Classification of isometries in dimension 2 and 3 			
7. Isometries Dialog, problem solving • Rotations in dimension 2 and 3 Dialog, problem solving • Displacements			
 Rotations in dimension 2 and 3 Displacements Classification of isometries in dimension 2 and 3 			
 Displacements Classification of isometries in dimension 2 and 3 			
Classification of isometries in dimension 2 and 3			
and 3			
8-9. Quadratic curves Dialog, problem solving Two tutorials			
Ellipse, hyperbola, parabola			
Canonical equations			
Relative position of a line			
Tangent lines			
10. Classification of quadrics (dimension 2 and 3) Dialog, problem solving			
Reducing to canonical form			
Isometric classification of quadrics			
Affine classification of quadrics			
11-12. Quadratic surfacesDialog, problem solvingTwo tutorials			
Ellipsoid, Cone, Hyperboloid, Paraboloid			
Canonical equation			
Tangent planes			
13. Curvatures Dialog, problem solving			
Curvature of curves			
Curvatures of surfaces			
14. Quaternions Dialog, problem solving			
Algebraic description			
Quaternions and rotations			
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[2] P.A. Blaga, Geometrie – material de curs, 2019.			
[3] M. Troyanov, Cours de géométrie, Lausanne, 2011.			

[4] E. Sernesi, Linear Algebra. A geometric Approach (Translated by J. Montaldi), 2009.

9. Corroborating the content of the discipline with the expectations of the epistemic community, professional associations and representative employers within the field of the program

- The material of this course serves other courses
 - a deeper understanding of linear algebra
 - affine transformations are necessary examples for a group theory course
 - \circ $\;$ quadrics are necessary examples in calculus courses
 - coordinate changes, projections, affine transformations are necessary for computer graphics
 - Applications of the theory are presented wherever appropriate

10. Evaluation

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Type of activity	10.1 Evaluation criteria	10.2 Evaluation methods	10.3 Share in the		
			grade (%)		
10.4 Course	Critical grasp of the	Two written partial exams	40% and 60%		
	learned material, ability to	at the middle and at the end	respectively		
	use what was learned	of the semester			
10.5 Seminar	Ability to use the theory	Points during the tutorial	Can lead up to one		
	for solving problems	for active participation	extra point for the		
			final grade		
10.6 Minimum performance standards					
75% attendance at the Seminar					
At least grade 5 for the final grade (excluding the bonus points obtained during the tutorials).					

Date

Signature of course coordinator

Signature of seminar coordinator

21. February 2024

Lect. Dr. Iulian Simion

Lect. Dr. Iulian Simion

Date of approval

Signature of the head of department

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