

# Pappus's harmonic theorem in the Einstein relativistic velocity model of hyperbolic geometry

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**Abstract.** In this note, we present a proof of Pappus's harmonic theorem in the Einstein relativistic velocity model of hyperbolic geometry.

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**Keywords:** Hyperbolic geometry, hyperbolic triangle, Pappus's harmonic theorem, gyrovector, Einstein relativistic velocity model.

## 1. Introduction

Hyperbolic geometry appeared in the first half of the 19<sup>th</sup> century as an attempt to understand Euclid's axiomatic basis for geometry. It is also known as a type of non-Euclidean geometry, being in many respects similar to Euclidean geometry. Hyperbolic geometry includes such concepts as: distance, angle and both of them have many theorems in common. There are known many main models for hyperbolic geometry, such as: Poincaré disc model, Poincaré half-plane, Klein model, Einstein relativistic velocity model, etc. The hyperbolic geometry is a non-Euclidian geometry. Here, in this study, we present a proof of Pappus's harmonic theorem in the Einstein relativistic velocity model of hyperbolic geometry. Pappus's harmonic theorem states that if  $A'B'C'$  is the cevian triangle of point  $M$  with respect to the triangle  $ABC$  such that the lines  $B'C'$  and  $BC$  meet at  $A''$ , then  $\frac{A''B}{A''C} = \frac{A'B}{A'C}$  [4].

Let  $D$  denote the complex unit disc in complex  $z$  - plane, i.e.

$$D = \{z \in \mathbb{C} : |z| < 1\}.$$

The most general Möbius transformation of  $D$  is

$$z \rightarrow e^{i\theta} \frac{z_0 + z}{1 + \overline{z_0}z} = e^{i\theta}(z_0 \oplus z),$$

which induces the Möbius addition  $\oplus$  in  $D$ , allowing the Möbius transformation of the disc to be viewed as a Möbius left gyrotranslation

$$z \rightarrow z_0 \oplus z = \frac{z_0 + z}{1 + \overline{z_0}z}$$

followed by a rotation. Here  $\theta \in \mathbb{R}$  is a real number,  $z, z_0 \in D$ , and  $\overline{z_0}$  is the complex conjugate of  $z_0$ . Let  $Aut(D, \oplus)$  be the automorphism group of the grupoid  $(D, \oplus)$ . If we define

$$gyr : D \times D \rightarrow Aut(D, \oplus), gyr[a, b] = \frac{a \oplus b}{b \oplus a} = \frac{1 + a\overline{b}}{1 + \overline{a}b},$$

then is true gyrocommutative law

$$a \oplus b = gyr[a, b](b \oplus a).$$

A gyrovector space  $(G, \oplus, \otimes)$  is a gyrocommutative gyrogroup  $(G, \oplus)$  that obeys the following axioms:

(1)  $gyr[\mathbf{u}, \mathbf{v}]\mathbf{a} \cdot gyr[\mathbf{u}, \mathbf{v}]\mathbf{b} = \mathbf{a} \cdot \mathbf{b}$  for all points  $\mathbf{a}, \mathbf{b}, \mathbf{u}, \mathbf{v} \in G$ .

(2)  $G$  admits a scalar multiplication,  $\otimes$ , possessing the following properties. For all real numbers  $r, r_1, r_2 \in \mathbb{R}$  and all points  $\mathbf{a} \in G$ :

(G1)  $1 \otimes \mathbf{a} = \mathbf{a}$

(G2)  $(r_1 + r_2) \otimes \mathbf{a} = r_1 \otimes \mathbf{a} \oplus r_2 \otimes \mathbf{a}$

(G3)  $(r_1 r_2) \otimes \mathbf{a} = r_1 \otimes (r_2 \otimes \mathbf{a})$

(G4)  $\frac{|r| \otimes \mathbf{a}}{\|r \otimes \mathbf{a}\|} = \frac{\mathbf{a}}{\|\mathbf{a}\|}$

(G5)  $gyr[\mathbf{u}, \mathbf{v}](r \otimes \mathbf{a}) = r \otimes gyr[\mathbf{u}, \mathbf{v}]\mathbf{a}$

(G6)  $gyr[r_1 \otimes \mathbf{v}, r_1 \otimes \mathbf{v}] = 1$

(3) Real vector space structure  $(\|G\|, \oplus, \otimes)$  for the set  $\|G\|$  of onedimensional "vectors"

$$\|G\| = \{\pm \|\mathbf{a}\| : \mathbf{a} \in G\} \subset \mathbb{R}$$

with vector addition  $\oplus$  and scalar multiplication  $\otimes$ , such that for all  $r \in \mathbb{R}$  and  $\mathbf{a}, \mathbf{b} \in G$ ,

(G7)  $\|r \otimes \mathbf{a}\| = |r| \otimes \|\mathbf{a}\|$

(G8)  $\|\mathbf{a} \oplus \mathbf{b}\| \leq \|\mathbf{a}\| \oplus \|\mathbf{b}\|$

**Theorem 1.1. (The Hyperbolic Theorem of Ceva in Einstein Gyrovector Space).** Let  $\mathbf{a}_1, \mathbf{a}_2$ , and  $\mathbf{a}_3$  be three non-gyrocollinear points in an Einstein gyrovector space  $(V_s, \oplus, \otimes)$ . Furthermore, let  $\mathbf{a}_{123}$  be a point in their gyroplane, which is off the gyrolines  $\mathbf{a}_1\mathbf{a}_2, \mathbf{a}_2\mathbf{a}_3$ , and  $\mathbf{a}_3\mathbf{a}_1$ . If  $\mathbf{a}_{123}$  meets  $\mathbf{a}_2\mathbf{a}_3$  at  $\mathbf{a}_{23}$ , etc., then

$$\frac{\gamma_{\ominus\mathbf{a}_1 \oplus \mathbf{a}_{12}} \|\ominus\mathbf{a}_1 \oplus \mathbf{a}_{12}\|}{\gamma_{\ominus\mathbf{a}_2 \oplus \mathbf{a}_{12}} \|\ominus\mathbf{a}_2 \oplus \mathbf{a}_{12}\|} \frac{\gamma_{\ominus\mathbf{a}_2 \oplus \mathbf{a}_{23}} \|\ominus\mathbf{a}_2 \oplus \mathbf{a}_{23}\|}{\gamma_{\ominus\mathbf{a}_3 \oplus \mathbf{a}_{23}} \|\ominus\mathbf{a}_3 \oplus \mathbf{a}_{23}\|} \frac{\gamma_{\ominus\mathbf{a}_3 \oplus \mathbf{a}_{13}} \|\ominus\mathbf{a}_3 \oplus \mathbf{a}_{13}\|}{\gamma_{\ominus\mathbf{a}_1 \oplus \mathbf{a}_{13}} \|\ominus\mathbf{a}_1 \oplus \mathbf{a}_{13}\|} = 1,$$

(here  $\gamma_{\mathbf{v}} = \frac{1}{\sqrt{1 - \frac{\|\mathbf{v}\|^2}{s^2}}}$  is the gamma factor).

(see [6, p. 461])

**Theorem 1.2. (The Hyperbolic Theorem of Menelaus in Einstein Gyrovector Space).** *Let  $\mathbf{a}_1, \mathbf{a}_2,$  and  $\mathbf{a}_3$  be three non-gyrocollinear points in an Einstein gyrovector space  $(V_s, \oplus, \otimes)$ . If a gyroline meets the sides of gyrotriangle  $\mathbf{a}_1\mathbf{a}_2\mathbf{a}_3$  at points  $\mathbf{a}_{12}, \mathbf{a}_{13}, \mathbf{a}_{23}$ , then*

$$\frac{\gamma_{\ominus\mathbf{a}_1\oplus\mathbf{a}_{12}} \|\ominus\mathbf{a}_1 \oplus \mathbf{a}_{12}\| \gamma_{\ominus\mathbf{a}_2\oplus\mathbf{a}_{23}} \|\ominus\mathbf{a}_2 \oplus \mathbf{a}_{23}\| \gamma_{\ominus\mathbf{a}_3\oplus\mathbf{a}_{13}} \|\ominus\mathbf{a}_3 \oplus \mathbf{a}_{13}\|}{\gamma_{\ominus\mathbf{a}_2\oplus\mathbf{a}_{12}} \|\ominus\mathbf{a}_2 \oplus \mathbf{a}_{12}\| \gamma_{\ominus\mathbf{a}_3\oplus\mathbf{a}_{23}} \|\ominus\mathbf{a}_3 \oplus \mathbf{a}_{23}\| \gamma_{\ominus\mathbf{a}_1\oplus\mathbf{a}_{13}} \|\ominus\mathbf{a}_1 \oplus \mathbf{a}_{13}\|} = 1.$$

(see [6, p. 463])

**Theorem 1.3. (The Gyrotriangle Bisector Theorem).** *Let  $ABC$  be a gyrotriangle in an Einstein gyrovector space  $(V_s, \oplus, \otimes)$ , and let  $P$  be a point lying on side  $BC$  of the gyrotriangle such that  $AP$  is a bisector of gyroangle  $\angle BAC$ . Then,*

$$\frac{\gamma_{|BP|} |BP|}{\gamma_{|PC|} |PC|} = \frac{\gamma_{|AB|} |AB|}{\gamma_{|AC|} |AC|}.$$

(see [7, p. 150])

For further details we refer to the recent book of A.Ungar [6].

**Definition 1.4.** *The symmetric of the median with respect to the internal bisector issued from the same vertex is called symmedian.*

**Theorem 1.5.** *If the gyroline  $AP$  is a symmedian of a gyrotriangle  $ABC$ , and the point  $P$  is on the gyroside  $BC$ , then*

$$\frac{\gamma_{|CP|} |CP|}{\gamma_{|BP|} |BP|} = \left( \frac{\gamma_{|CA|} |CA|}{\gamma_{|BA|} |BA|} \right)^2.$$

(See [3])

**Definition 1.6.** *We call antibisector of a triangle, the izotomic of a internal bisector of a triangle interior angle.*

## 2. Main results

In this section, we present a proof of Pappus's harmonic theorem in the Einstein relativistic velocity model of hyperbolic geometry.

**Theorem 2.1. (Pappus's harmonic theorem for hyperbolic gyrotriangle).** *If  $A'B'C'$  is the cevian gyrotriangle of gyropoint  $M$  with respect to the gyrotriangle  $ABC$  such that the gyrolines  $B'C'$  and  $BC$  meet at  $A''$ , then*

$$\frac{\gamma_{|A'B|} |A'B|}{\gamma_{|A'C|} |A'C|} = \frac{\gamma_{|A''B|} |A''B|}{\gamma_{|A''C|} |A''C|}.$$

*Proof.* If we use Theorem 1.1 in the gyrotriangle  $ABC$  (see Figure 1), we have

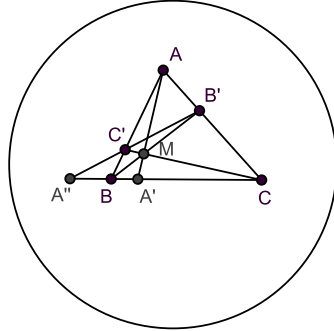


Figure 1

$$\frac{\gamma_{|A'B||A'B|}}{\gamma_{|A'C||A'C|}} \cdot \frac{\gamma_{|B'C||B'C|}}{\gamma_{|B'A||B'A|}} \cdot \frac{\gamma_{|C'A||C'A|}}{\gamma_{|C'B||C'B|}} = 1. \tag{2.1}$$

If we use Theorem 1.2 in the gyrotiangle  $ABC$ , cut by the gyroline  $A'A''$ , we get

$$\frac{\gamma_{|A''B||A''B|}}{\gamma_{|A''C||A''C|}} \cdot \frac{\gamma_{|B'C||B'C|}}{\gamma_{|B'A||B'A|}} \cdot \frac{\gamma_{|C'A||C'A|}}{\gamma_{|C'B||C'B|}} = 1. \tag{2.2}$$

From the relations (2.1) and (2.2) we have  $\frac{\gamma_{|A'B||A'B|}}{\gamma_{|A'C||A'C|}} = \frac{\gamma_{|A''B||A''B|}}{\gamma_{|A''C||A''C|}}$ .  $\square$

**Corollary 2.2.** *If  $A'B'C'$  is the cevian gyrotiangle of gyropoint  $M$  with respect to the gyrotiangle  $ABC$  such that the gyrolines  $B'C'$  and  $BC$  meet at  $A''$ , and  $AA'$  is a bisector of gyroangle  $\angle BAC$ , then*

$$\frac{\gamma_{|A''B||A''B|}}{\gamma_{|A''C||A''C|}} = \frac{\gamma_{|AB||AB|}}{\gamma_{|AC||AC|}}.$$

*Proof.* If we use Theorem 1.3 in the triangle  $ABC$ , we get

$$\frac{\gamma_{|A'B||A'B|}}{\gamma_{|A'C||A'C|}} = \frac{\gamma_{|AB||AB|}}{\gamma_{|AC||AC|}}. \tag{2.3}$$

If we use Theorem 2.1 in the triangle  $ABC$ , we get

$$\frac{\gamma_{|A'B||A'B|}}{\gamma_{|A'C||A'C|}} = \frac{\gamma_{|A''B||A''B|}}{\gamma_{|A''C||A''C|}}. \tag{2.4}$$

From the relations (2.3) and (2.4) we have  $\frac{\gamma_{|A''B||A''B|}}{\gamma_{|A''C||A''C|}} = \frac{\gamma_{|AB||AB|}}{\gamma_{|AC||AC|}}$ .  $\square$

**Corollary 2.3.** *If  $A'B'C'$  is the cevian gyrotiangle of gyropoint  $M$  with respect to the gyrotiangle  $ABC$  such that the gyrolines  $B'C'$  and  $BC$  meet at  $A''$ , and*

$AA'$  is a bisector of gyroangle  $\angle BAC$ , and  $AA_1$  is a antibisector of gyroangle  $\angle BAC$ , then

$$\frac{\gamma_{|A''B||A''B|}}{\gamma_{|A''C||A''C|}} = \left( \frac{\gamma_{|A_1B||A_1B|}}{\gamma_{|A_1C||A_1C|}} \right)^{-1}.$$

*Proof.* Because the gyroline  $AA_1$  is a isotomic line of the bisector  $AA'$ , then

$$\frac{\gamma_{|A_1B||A_1B|}}{\gamma_{|A_1C||A_1C|}} = \frac{\gamma_{|A'C||A'C|}}{\gamma_{|A'B||A'B|}} = \frac{\gamma_{|AC||AC|}}{\gamma_{|AB||AB|}}. \tag{2.5}$$

If we use Corollary 2.2, we have

$$\frac{\gamma_{|A''B||A''B|}}{\gamma_{|A''C||A''C|}} = \frac{\gamma_{|AB||AB|}}{\gamma_{|AC||AC|}}. \tag{2.6}$$

From the relations (2.5) and (2.6), we have

$$\frac{\gamma_{|A''B||A''B|}}{\gamma_{|A''C||A''C|}} = \left( \frac{\gamma_{|A_1B||A_1B|}}{\gamma_{|A_1C||A_1C|}} \right)^{-1}. \tag{2.7}$$

□

**Corollary 2.4.** If  $A'B'C'$  is the cevian gyrotriangle of gyropoint  $M$  with respect to the gyrotriangle  $ABC$  such that the gyrolines  $B'C'$  and  $BC$  meet at  $A''$ , and  $AA'$  is a symmedian of gyroangle  $\angle BAC$ , and the point  $A'$  is on the gyroside  $BC$ , then

$$\frac{\gamma_{|A''B||A''B|}}{\gamma_{|A''C||A''C|}} = \left( \frac{\gamma_{|AB||AB|}}{\gamma_{|AC||AC|}} \right)^2.$$

*Proof.* If we use Theorem 1.5, we have

$$\frac{\gamma_{|A'B||A'B|}}{\gamma_{|A'C||A'C|}} = \left( \frac{\gamma_{|AB||AB|}}{\gamma_{|AC||AC|}} \right)^2. \tag{2.8}$$

If we use Theorem 2.1, we have

$$\frac{\gamma_{|A''B||A''B|}}{\gamma_{|A''C||A''C|}} = \frac{\gamma_{|A'B||A'B|}}{\gamma_{|A'C||A'C|}}. \tag{2.9}$$

From the relations (2.8) and (2.9), we get  $\frac{\gamma_{|A''B||A''B|}}{\gamma_{|A''C||A''C|}} = \left( \frac{\gamma_{|AB||AB|}}{\gamma_{|AC||AC|}} \right)^2$ . □

**Theorem 2.5.** If  $A'B'C'$  is the cevian gyrotriangle of gyropoint  $M$  with respect to the gyrotriangle  $ABC$  such that the gyrolines  $B'C'$  and  $BC$  meet at  $A''$ , and  $AA'$  is a bisector of gyroangle  $\angle BAC$ , the gyrolines  $A'C'$  and  $BB'$  meet at  $D$ ,  $A'B'$  and  $CC'$  meet at  $E$ ,  $AD$  and  $BC$  meet at  $D'$ , and  $AE$  and  $BC$  meet in  $E'$ , then

$$\frac{\gamma_{|A''B||A''B|}}{\gamma_{|A''C||A''C|}} = \frac{\gamma_{|D'B||D'B|}}{\gamma_{|D'A'||D'A'|}} \cdot \frac{\gamma_{|E'A'||E'A'|}}{\gamma_{|E'C||E'C|}}.$$

*Proof.* If we use Theorem 1.1 in the gyrotriangle  $ABA'$  (see Figure 2),

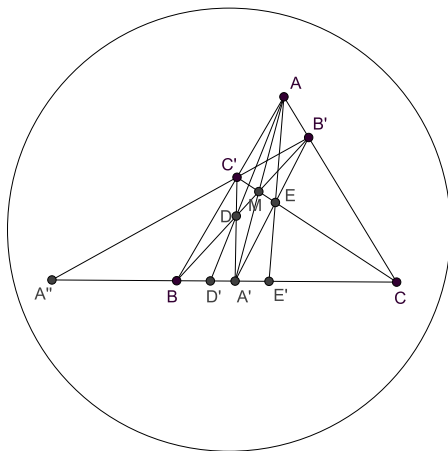


Figure 2

we have

$$\frac{\gamma_{|D'B||D'B|}}{\gamma_{|D'A'||D'A'|}} \cdot \frac{\gamma_{|C'A||C'A|}}{\gamma_{|C'B||C'B|}} \cdot \frac{\gamma_{|MA'||MA'|}}{\gamma_{|MA||MA|}} = 1. \tag{2.10}$$

If we use Theorem 1.2 in the gyrotriangle  $ABA'$ , cut by the gyroline  $CC'$ , we get

$$\frac{\gamma_{|CB||CB|}}{\gamma_{|CA'||CA'|}} \cdot \frac{\gamma_{|C'A||C'A|}}{\gamma_{|C'B||C'B|}} \cdot \frac{\gamma_{|MA'||MA'|}}{\gamma_{|MA||MA|}} = 1. \tag{2.11}$$

From the relations (2.10) and (2.11), we have

$$\frac{\gamma_{|D'B||D'B|}}{\gamma_{|D'A'||D'A'|}} = \frac{\gamma_{|CB||CB|}}{\gamma_{|CA'||CA'|}}. \tag{2.12}$$

Similarly, we obtain that

$$\frac{\gamma_{|E'C||E'C|}}{\gamma_{|E'A'||E'A'|}} = \frac{\gamma_{|BC||BC|}}{\gamma_{|BA'||BA'|}}. \tag{2.13}$$

If ratios the equations (2.12) and (2.13) among themselves, respectively, then

$$\frac{\gamma_{|D'B||D'B|}}{\gamma_{|D'A'||D'A'|}} \cdot \frac{\gamma_{|E'A'||E'A'|}}{\gamma_{|E'C||E'C|}} = \frac{\gamma_{|BA'||BA'|}}{\gamma_{|CA'||CA'|}}. \tag{2.14}$$

If we use Theorem 1.3 and the Corollary 2.2 in the triangle  $ABC$ , we get

$$\frac{\gamma_{|A'B||A'B|}}{\gamma_{|A'C||A'C|}} = \frac{\gamma_{|AB||AB|}}{\gamma_{|AC||AC|}} = \frac{\gamma_{|A''B||A''B|}}{\gamma_{|A''C||A''C|}}. \tag{2.15}$$

From the relations (2.14) and (2.15), we get

$$\frac{\gamma_{|D'B||D'B|}}{\gamma_{|D'A'||D'A'|}} \cdot \frac{\gamma_{|E'A'||E'A'|}}{\gamma_{|E'C||E'C|}} = \frac{\gamma_{|A''B||A''B|}}{\gamma_{|A''C||A''C|}}.$$

□

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