# QUASIPOSITIVE STURM-LIOUVILLE PROBLEM 

## YA. M. DYMARSKII


#### Abstract

We explain a new approach for investigation of quasilinear boundary problem by means of Sturm-Liouville problem.


## 1. The main result

In this paper, we consider the following nonlinear problem: find a classical solution $u \in C^{2}[0,1]$ of equation

$$
\begin{equation*}
-u^{\prime \prime}(x)+p\left(u(x), u^{\prime}(x), x\right) \cdot u(x)=f(x), \tag{1}
\end{equation*}
$$

under Dirichlet condition

$$
\begin{equation*}
u(0)=u(1)=0 \tag{2}
\end{equation*}
$$

We assume that

$$
\begin{equation*}
p \in C^{0}(\mathbf{R} \times \mathbf{R} \times[0,1]), \quad f \in C^{0}[0,1] \tag{3}
\end{equation*}
$$

We assume that the function $p$ is non-negative:

$$
\begin{equation*}
p(u, t, x) \geq 0 \text { for any }(u, t, x) \in \mathbf{R} \times \mathbf{R} \times[0,1] \tag{4}
\end{equation*}
$$

and there are such constant $C>0$ and continuous function $c: \mathbf{R} \rightarrow \mathbf{R}$ that

$$
\begin{equation*}
p(u, t, x) \leq C\left(c(u)+t^{2}\right) \tag{5}
\end{equation*}
$$

Received by the editors: 31.10 .2004 .
2000 Mathematics Subject Classification. 34L.
Key words and phrases. Quasipositive problem, inverse operator, fixed point.
This paper was presented at International Conference on Nonlinear Operators, Differential Equations
and Applications held in Cluj-Napoca (Romania) from August 24 to August 27, 2004.

Let $u^{*}$ be a solution of the nonlinear problem (1), (2). Then $u^{*}$ is the solution of the linear problem

$$
\begin{equation*}
\left[-\frac{d^{2}}{d x^{2}}+q(x)\right] u(x)=f(x), \quad u(0)=u(1)=0 \tag{6}
\end{equation*}
$$

with the positive operator $\left[-d^{2} / d x^{2}+q(x)\right]$ and the non-negative potential

$$
q(x)=p\left(u^{*}(x), u^{* \prime}(x), x\right) \geq 0
$$

Therefore the problem (1), (2) will be named quasipositive. Looking at the solution of nonlinear problem (1), (2) as a solution of linear problem (6), we shall introduce a new approach of passage from the boundary problem to a fixed point equation. There are several methods of passage (see [1-3]). Our approach is analogous to D.Gilbarg and N.Trudinger one ([2], chapter 11.3). The eigenfunction theory for quasipositive operators is developed in our papers $[4,5]$.

We formulate the principal result. Let

$$
K(x, \tau)=\left\{\begin{array}{l}
(1-x) \tau, 0 \leq \tau \leq x \\
x(1-\tau), x<\tau \leq 1
\end{array}\right.
$$

be the Green function of boundary problem

$$
-u^{\prime \prime}(x)=f(x), \quad u(0)=u(1)=0
$$

Theorem 1. The problem (1)-(5) has at least one solution $u \in C^{2}[0,1]$. For any solution the estimate

$$
\begin{equation*}
\int_{0}^{1}\left(u^{\prime}(x)\right)^{2} d x \leq \int_{0}^{1}\left(\int_{0}^{1} K_{x}^{\prime}(x, \tau) f(\tau) d \tau\right)^{2} d x \tag{7}
\end{equation*}
$$

is true.
We note that the estimate (7) does not depend on "potential" $p=p(u, t, x)$. It is a direct consequence of the non-negative condition (4).

## 2. The operator equation

Introduce following notations. As usual, we denote $L_{k}(0,1)(k=1,2)$ the space of functions on $(0,1)$ which are $k$ integrable. The Sobolev space of functions $u \in L_{2}(0,1)$ with distributional derivative which are integrable square we denote by $W_{2}^{1}(0,1) ; \stackrel{\circ}{W_{2}^{1}}(0,1) \subset W_{2}^{1}(0,1)$ is the closure in $W_{2}^{1}(0,1)$ of subspace of $C^{\infty}$ _ functions, which are equal to zero outside some segment $[\alpha, \beta] \subset(0,1)$. The norm of $u \in W_{2}^{1}(0,1)$ is $\|u\|_{1}=\sqrt{\int_{0}^{1}\left(\left(u^{\prime}\right)^{2}(x)+u^{2}(x)\right) d x}$; the norm of $u \in \stackrel{\circ}{W_{2}^{1}}(0,1)$ is $\|u\|_{1}^{\circ}=\sqrt{\int_{0}^{1}\left(u^{\prime}\right)^{2}(x) d x}$. The norms $\|u\|_{1}$ and $\|u\|_{1}^{\circ}$ are equivalent on the space $\stackrel{\circ}{W_{2}^{2}}(0,1)$ due to the boundary condition (2) (see [1], chapter 13.7). Moreover, space $\stackrel{\circ}{W_{2}^{1}}(0,1)$ is Hilbert one with the inner product $(u, v)^{\circ}=\int_{0}^{1} u^{\prime} v^{\prime} d x$.

First we are interested in solutions (of problem (1), (2)) from the space $\stackrel{\circ}{W}_{2}^{1}$ $(0,1)$. As usual, multiplying both sides of the equation (1) by $v \in \stackrel{\circ}{W_{2}^{1}}(0,1)$ and integrating by parts, we get

$$
\begin{gather*}
\int_{0}^{1} u^{\prime} v^{\prime} d x+\int_{0}^{1}\left(\int_{0}^{1} K(x, \tau) p\left(u(\tau), u^{\prime}(\tau), \tau\right) u(\tau) d \tau\right)^{\prime} v^{\prime} d x \\
=\int_{0}^{1}\left(\int_{0}^{1} K(x, \tau) f(\tau)\right)^{\prime} v^{\prime} d x \tag{8}
\end{gather*}
$$

A function $u \in \stackrel{\circ}{W_{2}^{1}}(0,1)$ is called a weak solution of the problem (1), (2) if for every $v \in \stackrel{\circ}{W}_{2}^{1}(0,1)$ the equation (8) is valid. By the inner product, the identity (8) is of the following form

$$
\begin{equation*}
(u, v)^{\circ}+(P(u), v)^{\circ}=(\mathbf{f}, v)^{\circ} \tag{9}
\end{equation*}
$$

where

$$
\begin{align*}
P: \stackrel{\circ}{W_{2}^{1}}(0,1) \rightarrow \stackrel{\circ}{W_{2}^{1}}(0,1), \quad P(u) & =\int_{0}^{1} K(x, \tau) p\left(u(\tau), u^{\prime}(\tau), \tau\right) u(\tau) d \tau  \tag{10}\\
\quad \mathbf{f} & \stackrel{\circ}{W_{2}^{1}}(0,1), \quad \mathbf{f} \tag{11}
\end{align*}
$$

Since (9) is valid for every function $v \in \stackrel{\circ}{W_{2}^{1}}(0,1)$, the identity (9) is equivalent to the operator equation

$$
\begin{equation*}
u+P(u)=\mathbf{f} \tag{12}
\end{equation*}
$$

## 3. The quasilinear representation of $P$

Now we investigate the operator $P\left(\right.$ see (10)) in more detail. By $L\left(\stackrel{\circ}{W_{2}^{1}}(0,1)\right)$ denote the Banach space of continuous linear maps A which operate in $\stackrel{\circ}{W_{2}^{1}}(0,1)$ and by $\operatorname{Lis}\left(\stackrel{\circ}{W_{2}^{1}}(0,1)\right) \subset L\left(\stackrel{\circ}{W_{2}^{1}}(0,1)\right)$ the open subset of linear isomorphisms. As usually, the norm $\|\mathbf{A}\|=\sup \|\mathbf{A} v\|_{1}^{\circ}$ where $\|v\|_{1}^{\circ}=1$. Consider the map

$$
\begin{gathered}
A: \stackrel{\circ}{W_{2}^{1}(0,1)} \rightarrow L\left(\stackrel{\circ}{W_{2}^{1}}(0,1)\right), \quad A(u)=\mathbf{A} \text { that } \forall v \in \stackrel{\circ}{W_{2}^{1}}(0,1) \\
\mathbf{A} v=\int_{0}^{1} K(x, \tau) p\left(u(\tau), u^{\prime}(\tau), \tau\right) v(\tau) d \tau
\end{gathered}
$$

Clearly $P(u)=A(u) u$. We shall call $A$ the quasilinear representation of the map $P$ [5]. Now the equation (12) is of the following form

$$
\begin{equation*}
(\mathbf{E}+A(u)) u=\mathbf{f}, \tag{13}
\end{equation*}
$$

where $\mathbf{E}$ is identity mapping. Properties of the map $A$ is in next lemma.
Lemma 1. 1) For every $u \in \stackrel{\circ}{W_{2}^{1}}(0,1)$ the linear operator $A(u) \in L\left(\stackrel{\circ}{W_{2}^{1}}(0,1)\right)$ is completely continuous.
2) The map $A$ is completely continuous.
3) For every $u \in \stackrel{\circ}{W_{2}^{1}}(0,1)$ the $\operatorname{map} \mathbf{E}+A(u) \in \operatorname{Lis}\left(\stackrel{\circ}{W_{2}^{1}}(0,1)\right)$ and

$$
\begin{equation*}
\left\|(\mathbf{E}+A(u))^{-1}\right\|<1 \tag{14}
\end{equation*}
$$

Proof. Since for any $u, v \in \stackrel{\circ}{W_{2}^{1}}(0,1)$

$$
((A(u) v)(x))^{\prime}=\int_{0}^{1} K_{x}^{\prime}(x, \tau) p\left(u(\tau), u^{\prime}(\tau), \tau\right) v(\tau) d t
$$

and the function $r(\xi)=p\left(u(\xi), u^{\prime}(\xi), \xi\right) v(\xi) \in L_{1}(0,1)$ is integrable one (see (5)), the function $(A(u) v)^{\prime} \in C^{0}[0,1]$. Thus the map $\mathbf{A}=A(u): \stackrel{\circ}{W_{2}^{1}}(0,1) \rightarrow\left\{C^{1}[0,1] \cap(2)\right\}$ is continuous. Embedding im : $\left\{C^{1}[0,1] \cap(2)\right\} \subset \stackrel{\circ}{W}_{2}^{1}(0,1)$ is completely continuous ([1], chapter 26.24). Hence the linear operator $A(u)=i m \cdot A(u)$ is completely continuous as the composition of continuous and completely continuous maps [6].

To prove the second statement, we represent the map $A$ in the form

$$
A(u) v=-x \int_{0}^{1}\left(\int_{0}^{\tau}\left(\int_{0}^{\xi} p\left(u(\nu), u^{\prime}(\nu), \nu\right) d \nu\right) v^{\prime}(\xi) d \xi\right) d \tau+
$$

QUASIPOSITIVE STURM-LIOUVILLE PROBLEM

$$
\int_{0}^{x}\left(\int_{0}^{\tau}\left(\int_{0}^{\xi} p\left(u(\nu), u^{\prime}(\nu), \nu\right) d \nu\right) v^{\prime}(\xi) d \xi\right) d \tau
$$

Write map $A$ as the composition of four maps: $A=\delta \cdot \gamma \cdot \beta \cdot \alpha$, where

$$
\begin{gathered}
\alpha: \stackrel{\circ}{W}_{2}^{1}(0,1) \rightarrow L_{1}(0,1), \quad \alpha(u):=p\left(u(\xi), u^{\prime}(\xi), \xi\right)=q \\
\beta: L_{1}(0,1) \rightarrow C^{0}[0,1], \quad \beta(q):=\int_{0}^{\xi} q(\nu) d \nu=s ; \\
\gamma: C^{0}[0,1] \subset L_{2}(0,1), \quad \gamma(s):=s \text { is the natural embedding; } \\
\delta: L_{2}(0,1) \rightarrow L\left(\stackrel{\circ}{W}_{2}^{1}(0,1)\right), \quad \delta(s)=\mathbf{A} \text { that } \forall v \in \stackrel{\circ}{W}_{2}^{1}(0,1) \\
\mathbf{A}(v)=-x \int_{0}^{1}\left(\int_{0}^{\tau} s(\xi) v^{\prime}(\xi) d \xi\right) d \tau+\int_{0}^{x}\left(\int_{0}^{\tau} s(\xi) v^{\prime}(\xi) d \xi\right) d \tau .
\end{gathered}
$$

These maps are continuous and the map $\gamma$ is completely continuous. This completes the proof of the second statement.

For any $u, v \in \stackrel{\circ}{W_{2}^{1}}(0,1)$ we have

$$
\begin{aligned}
\left(\|(\mathbf{E}+A(u)) v\|_{1}^{\circ}\right)^{2}= & (v, v)^{\circ}+2(A(u) v, v)^{\circ}+(A(u) v, A(u) v)^{\circ} \geq \\
& \left(\|v\|_{1}^{\circ}\right)^{2}+2(A(u) v, v)^{\circ} .
\end{aligned}
$$

Since (see (4))

$$
(A(u) v, v)^{\circ}=\int_{0}^{1} p\left(u(x), u^{\prime}(x), x\right) v^{2}(x) d x \geq 0
$$

then

$$
\left(\|(\mathbf{E}+A(u)) v\|_{1}^{\circ}\right)^{2} \geq\left(\|v\|_{1}^{\circ}\right)^{2} .
$$

Whence we obtain the third statement.

## 4. Proof of Theorem

Next step is the passage from the non-homogeneous equation (13) to a fixed point equation.

Lemma 2. 1) The equation (13) is equivalent to the operator equation

$$
\begin{equation*}
u=(\mathbf{E}+A(u))^{-1} \mathbf{f} . \tag{15}
\end{equation*}
$$

2) For any weak solution $u$ the following a priori estimate is valid:

$$
\begin{equation*}
\|u\|_{1}^{\circ} \leq\|\mathbf{f}\|_{1}^{\circ} . \tag{16}
\end{equation*}
$$

3) The map

$$
B: \stackrel{\circ}{W_{2}^{1}}(0,1) \rightarrow \stackrel{\circ}{W_{2}^{1}}(0,1), \quad B(u):=(\mathbf{E}+A(u))^{-1} \mathbf{f}
$$

is completely continuous.
Proof. The first statement follows from the third statement of Lemma 1. The second statement follows from the first one and third statement of Lemma 1 (see (14)).

The map $B$ is the composition:

$$
u \rightarrow A(u) \rightarrow \mathbf{E}+A(u) \rightarrow(\mathbf{E}+A(u))^{-1} \rightarrow(\mathbf{E}+A(u))^{-1} \mathbf{f}
$$

The first map is completely continuous (see the second statement of Lemma 1) and the others maps are continuous. This completes the proof [6].

Note that the map $B=(\mathbf{E}+A(u))^{-1} \mathbf{f}$ depends on the $u$ in the operator part only. Thus properties of equation (15) follow from properties of map $A$.

To proof Theorem, we apply Leray-Schauder degree. Let the ball $T_{R}=$ $\left\{u \in \stackrel{\circ}{W_{2}^{1}}(0,1):\|u\|_{1}^{\circ} \leq R\right\}$, where the constant $R>\|\mathbf{f}\|_{1}^{\circ}$. Let the sphere $S_{R}=$ $\left\{u \in W_{2}^{1}(0,1):\|u\|_{1}^{\circ}=R\right\}$. By (14) and (15), for any $u \in S_{R}$ we obtain $\|u\|_{1}^{\circ}>$ $\|B(u)\|_{1}^{\circ}$. Therefore on $S_{R}$ the completely continuous vector field $u-B(u) \neq 0$ and degree of $B$ is equal to one [6]. Consequently there is a solution $u \in T_{R}$ of equation (15). The existence of a weak solution is proved.

By (16) and (11) we obtain

$$
\int_{0}^{1}\left(u^{\prime}(x)\right)^{2} d x \leq \int_{0}^{1}\left\{\left(\int_{0}^{1} K(x, \tau) f(\tau) d \tau\right)_{x}^{\prime}\right\}^{2} d x=\int_{0}^{1}\left(\int_{0}^{1} K_{x}^{\prime}(x, \tau) f(\tau) d \tau\right)^{2} d x
$$

The estimate (7) is proved.
Actually, the weak solution $u \in \stackrel{\circ}{W_{2}^{1}}(0,1)$ is the classical solution, i.e. $u \in$ $C^{2}[0,1]$. This follows from well known theorem about regularity of weak solution (see [1], §17). Theorem is proved.

## References

[1] Fuc̆ik S., Kufner A., Nonlinear differential equation, Elsevier Scientific Publishing Company, Amsterdam-Oxford-New York, (1980).
[2] Gilbarg D., Trudinger Neil S., Differential equation of second order, Springer-Verlag, Berlin-Heidelberg-New York-Tokio, (1983).
[3] Skripnik I.V., Methods of investigation of nonlinear elliptic boundary value problems, Nauka, Moscow, (1990).
[4] Dymarskii Ya.M., The periodic Choquard equation, Operator Theory: Adv. Appl. 117, 87-99 (2000).
[5] Dymarskii Ya.M., Intersection number and eigenvectors of quasiliner Hilbert-Schmidt operators, Matematicheskaya fizika, analiz, geometriya 9, No. 4, 604-621 (2002).
[6] Krasnosel'skii M.A., Topological methods in the theory of nonlinear integral equations, Pergamon Press, New York, (1964).

Department of Mathematical Analysis,
Lugansk National Pedagogical University, Oboronnaya str. 2,
Lugansk 91011, Ukraine
E-mail address: dymarsky@lep.lg.ua

